The computational fluid dynamics performance analysis of horizontal axis wind turbine

Naji Abdullah Mezaal¹, Osintsev K. V.², Alyukov S.V.³
¹ Master in Heat and Power Engineering, South Ural State University, Russian Federation
²,³ Departement of Heat and Power Engineering, South Ural State University, Russian Federation

ABSTRACT
Computational fluid dynamics (CFD) simulations were performed in the present study using ANSYS Fluent 18.0, a commercially available CFD package, to characterize the behaviour of the new HAWT. Static three-dimensional CFD simulations were conducted. The static torque characteristics of the turbine and the simplicity of design highlight its suitability for the GE 1.5xle turbine. The major factor for generating the power through the HAWT is the velocity of air and the position of the blade angle in the HAWT blade assembly. The paper presents the effect of the blade is 43.2 m length and starts with a cylindrical shape at the root then transitions to the airfoils S818, S825 and S826 for the root, body and tip respectively. This blade also has pitch to vary as a function of radius, giving it a twist and the pitch angle at the blade tip is 4 degrees. This blade was created to be similar in size to a GE 1.5xle turbine by Cornell University. In addition, note that to represent the blade being connected to a hub, the blade root is offset from the axis of rotation by 1 meter. The hub is not included in our model. The experimental analysis of GE 1.5xle turbine, so that possible the result of CFD analysis can be compared with theoretical calculations. CFD workbench of ANSYS is used to carry out the virtue simulation and testing. The software generated test results are validated through the experimental readings. Through this obtainable result will be in the means of maximum constant power generation from HAWT.

Keywords:
Airfoils (S818, S825, S826)
CFD
Horizontal axis Wind Turbine
Modelling and Simulation
Power coefficient (Cp)
WT_Perf analysis

1. INTRODUCTION
The focus on Renewable Energy Resources has increased significantly in the recent years in the wake of growing environmental pollution, rising energy demand and depleting fossil fuel resources. Different sources of renewable energy include biomass, solar, geothermal, hydroelectric, and wind. Among these resources, the wind turned out to be a cheaper alternative energy resource, and, therefore, extensive research efforts were made to improve the technology of electricity generation by wind. The world has enormous potential of wind energy that can be utilized for electricity generation. Currently, large scale HAWTs are not economically attractive; however, they offer energy solutions for remote places away from the main distribution lines and places where large wind farms cannot be installed due to environmental concerns and small scale dispersed generation units are preferred. In this paper, the blade was created to be similar in size to a GE 1.5xle turbine that used to validate the CFD results, where the experimental data of GE 1.5xle turbine can be compared with theoretical calculations and CFD analysis of this paper. In the following sections we will show the purpose of this paper.
This study considers the deformation due to aerodynamic loading of a wind turbine blade by performing a steady-state 1-way FSI (Fluid-Structure Interaction) analysis. This study uses ANSYS Fluent 18.0 to develop the aerodynamics loading on the blade. The blade is 43.2 meters long, the blade is made out of an orthotropic composite material, it has a varying thickness and it has a spar inside the blade for structural rigidity. These specs, which are important for the FEA simulation.

The main objective of this paper is to analyze the flow field around the horizontal axis wind turbine by numerically solving the governing equations using a finite-volume method and Reynolds’s Averaged Navier-Stokes (RANS) approach [3]. Upstream and downstream wake visualization in terms of x, y and z-velocities are in the scope of the paper. Also, tangential velocity at the tip of the blade will be plotted and compared with theoretical results. The other objective of the paper works is to determine the efficiency and power extracted by wind turbines [4]. The project is structured as follows:

a. Modelling the one-third of the wind turbine rotor by means of 120° periodicity. Select the geometry of the blade shape by Block Element Modifier (BEM) designing techniques.

b. Create the 3-D model of the blade profile and blade for the simulation in SOLID-WORK.

c. Create computational domain for flow field analysis and generate high quality mesh.

d. Create the cavity model for the cavity analysis for the CFD analysis and simulation.

e. Calculate the power extracted by the turbine.

f. Comparison of the software simulation data and theoretical calculations of GE 1.5xle turbine.

g. Validation of the result will be done.

In this section of the study, the blade geometry is imported, a mesh is created around the blade and the fluent solver is then used to find the aerodynamics loading on the blade, the fluid streamlines and the torque generated. We will use air at standard conditions (15-degree Celsius). Its density is 1.225 kg/m³ and its viscosity is 1.7894e-05 kg/ (m*s). Using periodicity, we will simulate the flow around one blade and extrapolate the solution to two more blades in order to visualize the results for a 3-blade rotor.

Analysis of the blade in the analytical mode gives useful results of the first pass about stresses and moments that are useful in determining the basic requirements for strength and materials. This type of analytical analysis, though useful, is insufficient to properly evaluate the full wind turbine blade. Accordingly, we sought to use finite element analysis to more accurately capture the loads and stresses generated on the blade geometry by particular loading scenarios. This computational method allows for much greater flexibility in testing out various loads and blade geometries, allowing for an iterative approach to developing our turbine blade. First, we began by selecting our airfoils. We decided to use the NREL S-series of airfoil as described in (Malcolm and Hansen 2006). These airfoils are in general somewhat thicker than the types typically seen on airplanes due to structural concerns, and are largely insensitive to roughness. As such, they are well suited for turbine blades. Figure 1 shows turbine blade airfoils (S818, S825, S826).

Figure 1. Turbine blade airfoils (S818, S825, S826)

The beginning of the blade is the circular hub section. This circular root transitions into the S818 airfoil, which then transitions to the S825 airfoil, which then transitions into the S826 airfoil used at the tip. All geometry of the blade, including the length of the twist, span and chord, was determined using the WT_Perf analysis and can be seen below in Table 2 [1-2].

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Table 1. Turbine blade geometry

<table>
<thead>
<tr>
<th>Relm (%span)</th>
<th>Span (m)</th>
<th>Twist (deg)</th>
<th>Chord (% span)</th>
<th>Chord (m)</th>
<th>Airfoil</th>
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<td>0.07543</td>
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With the given geometry of the blade, we start the process of creating the blade for our FEA model. Although we can simulate and analyze the full wing using ANSYS, so we decided to model the blade using the SolidWorks CAD package instead. Because we can import geometry directly from SolidWorks to ANSYS, this seemed to be the most effective way to manage the creation of the blade [1-2].

2. MATHEMATICAL MODEL

The turbulent wind flows towards the negative z-direction at 12 m/s, which is a typical rated wind speed for a turbine this size. This incoming flow assumed to make the blade rotate at an angular velocity of 2.22 rad/s about the z-axis (the blade is thus spinning clockwise when looking at it from the front, like most real wind turbines). The tip speed ratio (TSR) (the ratio of the blade tip velocity to the incoming wind velocity) is therefore equal to 8 which is a reasonable value for a large wind turbine. Note that to represent the blade being connected to a hub, the blade root is offset from the axis of rotation by 1 meter. The hub is not included in our model.

2.1. Governing equations

The governing equations are the continuity and Navier-Stokes equations. These equations are written in a frame of reference rotating with the blade. This has the advantage of making our simulation not require a moving mesh to account for the rotation of the blade [5]. The equations that we will use look as follows:

Conservation of mass:

\[ \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 \]  \quad (1)

Conservation of Momentum (Navier-Stokes):

\[ \nabla \cdot (\rho \mathbf{v} \mathbf{v}) + \rho (2\sigma - \nabla \times \mathbf{v}) + \sigma \times \mathbf{v} + \mathbf{v} \times \sigma \times r = - \nabla p + \nabla \tau r \]  \quad (2)

Where:

\( \mathbf{v} \) is the relative velocity (the velocity viewed from the moving frame) and 
\( \sigma \) is the angular velocity [5].

Note the additional terms for the Coriolis force \( (2\sigma \times \mathbf{v}) \) and the centripetal acceleration \( (\sigma \times \sigma \times r) \) in the Navier-Stokes equations. In Fluent, we’ll turn on the additional terms for a moving frame of reference and input \( \sigma = -2.22 \text{ rad/sec} \). Important: We use the Reynolds Averaged form of continuity and momentum and use the SST k-omega turbulence model to close the equation set [6]-[7].

2.2. Boundary conditions

We model only 1/3 of the full domain using periodicity assumptions.
\[ \vec{v}(r_i, \theta) = \vec{v}(r_i, \theta_1 - 120^\circ n) \quad \text{for } n = 1, 2, 3... \]

Figure 2 shows periodicity assumptions.

\[ \vec{v}(r_1, \theta) = \vec{v}(r_1, \theta_1 - 120^\circ n) \]
\[ = \vec{v}(r_1, 240^\circ - 120^\circ (1)) = \vec{v}(r_1, 120^\circ) \]
\[ = \vec{v}(r_1, 240^\circ - 120^\circ (2)) = \vec{v}(r_1, 60^\circ) \]

This therefore proves that the velocity distribution at theta of 0 and 120 degrees are the same. If we denote theta_1 to represent one of the periodic boundaries for the 1/3 domain and theta-2 being the other boundary, then

\[ \vec{v}(r_1, \theta_1) = \vec{v}(r_1, \theta_2) \]
\[ v(r_i, \theta_1) = v(r_i, \theta_2) \]

The boundary conditions on the fluid domain are as follows:

- **Inlet**: Velocity of 12 m/s with turbulent intensity of 5% and turbulent viscosity ratio of 10,
- **Outlet**: Pressure of 1 atm,
- **Blade**: No-slip,
- **Side Boundaries**: Periodic [3].

### 2.3. Numerical solution procedure in ANSYS

FLUENT converts these differential equations into a set of algebraic equations. Inverting these algebraic equations gives the value of \((u, v, w, p, k, \text{and } \omega)\) at the cell centers. Everything else is derived from the cell centers values (post-processing). In our mesh, we’ll have around 10000000 cells. The total number of unknowns and hence algebraic equations is:

\[ 10,000,000 \times 6 = 60 \text{ million} \]

This huge set of algebraic equations is inverted through an iterative process. The matrix to be inverted is huge but sparse. In FLUENT, we will use the pressure-based solver.

### 2.4. Hand-calculations of expected results

According to the specification sheet of the turbine GE 1.5 xle wind, one simple hand-calculation that we can do now before even starting our simulation is to find theoretical wind velocity at the tip. We can then

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later compare our answer with what we get from our simulation to verify that they agree. The velocity (v), on
the blade should follow the formula:

\[ v = r \cdot \omega \]  \hspace{1cm} (3)

Plugging in our angular velocity of 2.22 rad/s and using the blade length of 43.2 meters plus 1 meter to
account for the distance from the root to the hub, we get 44.2 m.

\[ v = 2.22 \cdot 44.2 \approx 98.12 \text{ m/s} \]

Additionally, by using the simple one-dimensional momentum theory, we can estimate the power
coefficient which is the fraction of harnessed power to total power in the wind for the given turbine swept
area. This analysis uses the following assumptions:

a. The flow is steady, homogenous and incompressible.
b. There is no frictional drag.
c. There is an infinite number of blades.
d. There is uniform thrust over the disc or rotor area.
e. The wake is non-rotating.
f. The static pressure far upstream and downstream of the rotor is equal to the undisturbed
ambient pressure.

According to this blade is meant to resemble GE 1.5 xle wind turbine blade [8]. The specification
sheet of this turbine states the rated power of this turbine to be 1.5MW, the rated wind speed to be 11.5 m/s
and the rotor diameter to be 82.5 m. A power and power coefficient [9] is then defined as:

\[ P = T \cdot \omega \]  \hspace{1cm} (4)

\[ C_p = \frac{P_{\text{rated}}}{P_{\text{wind}}} = \frac{P_{\text{rated}}}{0.5 \rho AV_{\text{rated}}^3} \]  \hspace{1cm} (5)

\[ C_p = \frac{1500000}{0.5 \cdot (1.225) \left( \frac{82.5}{4} \right)} (11.5^3) = 0.3 \]

The resulting power coefficient of 0.3 it is very reasonable. We will compare it to power coefficient
obtained from the simulation in the Verification and Conclusion section.

2.5. Betz equation and criterion

The Betz Equation deals with the wind speed upstream \( V_0 \) and the downstream \( V_d \) wind speed of the
turbine. The value of the Betz limit suggests that a wind turbine can be extracted at most 59.3 percent of
energy in an undisturbed wind speed stream [11], it can be defined as:

Betz coefficient=\( C_p = \frac{16}{27} = 0.592593 = 59.3\% \)

Lanchester–Betz–Joukowsky limit [10] shows that the actual turbine cannot extract more than 59.3\% of the
power in an undisturbed tube of air of the same as shown in Figure 3 [4-11].
2.6. Power coefficient

The power generated by the kinetic energy of a free flowing wind stream is shown in the Figure 3, where is defined as the ratio of the power extracted by the wind turbine relative to the energy available in the wind stream. Power coefficient (Cp), represented as extracted power over the total power, it can be expressed by the induction factor (a) as:

\[ C_p = 4a(1 - a)^2 \]  

(6)

Where (a) is Induction factor, the fractional decrease in wind velocity between the free stream and rotor plane can be expressed in terms of an axial induction factor, a:

\[ a = \frac{v_a - v}{v_0} \]  

(7)

Where, \( V \) is the velocity at the disk and it is defined by:

\[ v = \frac{1}{2}(v_0 + v_3) \]  

(8)

\( V_0 \) and \( V_3 \) are free stream and downstream velocities respectively. The amount of axial induction factor determines the amount of power extracted by turbine [4].

3. RESEARCH METHOD

3.1. Geometry and mesh generation

In the following section, we will create our geometry and the blade volume from the fluid geometry as shown in Figure 4. As we mentioned in boundary condition part as showed in Figure 2 periodicity assumptions.

Grid generation is often considered as the most time consuming part of CFD simulation. We start off by naming various faces of our geometry for later use in FLUENT and to make surface body referencing much easier when creating our mesh as shown in Figure 5. After several attempts to mesh the geometry we have been obtained on this good number of mesh, our geometry has a high quality mesh around 10884336 elements as shown in Figure 6, this is considering a very fine enough to obtain a sufficiently accurate solution. We are applying specifying some global mesh settings which means that these settings will be applied to the whole mesh altogether. After applying controls to the whole mesh, we now apply mesh settings to specific areas of our geometry.
4. RESULTS AND ANALYSIS

4.1. Blade velocity

In CFD-Post for the numerical results. We will enable the visualization of a full 3-blade rotor as shown in Figure 7. First, a hand-calculation is did based on the classical aerodynamic theory in order to find the theoretical wind velocity at the tip. This data is comparing with the value of the velocity obtained by ANSYS. Figure 7 and illustrate that the local wind turbine blade velocity increases with radius because of the rotation of the blades. The velocity of the tip, which is the highest velocity, it is around 98.14 m/s, the same value as equation.

Figure 6. Mesh geometry generation with number of mesh elements in ANSYS Fluent
4.2. Velocity streamlines

Wind velocity streamline shows the velocity of the fluid domain around the three wind turbine blades, see Figure 8 shows visualize the flow around the turbine using velocity streamlines:

![Velocity Streamlines](image)

Figure 8. Blade velocity streamlines

Note that the legend bar in the above picture presents a color graduation from blue, which is the lowest velocity, until red. Inlet section ($V_0$) has yellow color so it is 12 m/s, as it was mentioned earlier. The color blue in the streamlines means that when the airflow passes the blades ($V_s$) so it is 10 m/s, it suffers a slowing down and the velocity decreases. Clearly, an acceleration of the flow around the wake is represented by red color. All these features match the mass conservation and momentum theory.

5. VERIFICATION

From the Figure 8 and by applying (6) to (8) for obtaining the efficiency ($C_p$) of the turbines is the implementation of the Actuator Disk Theory. Free stream velocity $V_0$ and downstream velocity $V_s$, are obtained from CFD and (6) to (8) will again result the power coefficient ($C_p$) is 0.298.

The value of the velocity obtained by ANSYS Figure 7 illustrate that the local wind turbine blade velocity increases with radius because of the rotation of the blades. The velocity of the tip, which is the highest velocity, it is around 98.14 m/s, the same value as (3). The Torque is a force that turns or rotates the wind turbine and it is equal to the force multiplied by distance. This means that so longer blades are, more torque can generate. The value that we have been obtained from our CFD analysis for one blade is 421910 n.m. and by applying (4) we have power is 936.64 kW. Now we can compare the CFD results and mathematic calculations with the experimental data of GE1.5 xle turbine in the Table 2.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Theoretical calculations</th>
<th>GE1.5 xle turbine</th>
<th>CFD analysis</th>
</tr>
</thead>
<tbody>
<tr>
<td>Velocity ($v$) m/s</td>
<td>98.12</td>
<td>97</td>
<td>98.14</td>
</tr>
<tr>
<td>Power coefficient ($C_p$)</td>
<td>0.59</td>
<td>0.265</td>
<td>0.298</td>
</tr>
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</table>

6. CONCLUSION

In the present investigation, the aerodynamic efficiency of the horizontal axis wind turbine using computational methods of fluid dynamics is studied. The obtained CFD results are compared with the mathematical calculation and experimental data of the GE1.5 xle turbine. This study has demonstrated that the CFD methods confirm the experimental results and can be used to optimize and confirmation the shape Specifications of the turbine. According to the results of this research, it can be concluded that the power coefficient of the turbine is actually matches to the theoretical results as demonstrated.
REFERENCES


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