

## Comparison between proposed fuzzy logic and ANFIS for MPPT control for photovoltaic system

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### ABSTRACT

In this paper, a maximum power point tracking (MPPT) algorithm for photovoltaic (PV) systems is achieved based on fuzzy logic controller (FLC) and compared with an anfis (neuro-fuzzy) based mppt controller, this method allies the abilities of artificial neural networks in learning and the power of fuzzy logic to handle imprecise data. Both methods are simulated using matlab/ simulink. The choice of power variation and the current variation as inputs of the proposed controllers reduce the calculation. Both FLC and ANFIS based MPPT are tested in terms of steady state performance and the pv system dynamic.

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## 1. INTRODUCTION

During the last years, urgent needs for a new energy alternative in order to overcome the energy crisis and global warming issues. Those problems have significantly promoted the renewable energies growth. Undeniably, the photovoltaic systems represent a very competitive solution. Unfortunately, this solution is not perfect due to bad efficiency of the energy conversion; to overcome this problem it is necessary to provide the PV system with an MPPT controller to gather the maximum electrical power from the photovoltaic modules in different working conditions [1]. Therefore many methods of MPPT were completed in preceding studies, as Perturb and Observe (P&O) [2], fractional open-circuit voltage [3], fractional short-circuit current, incremental [3] conductance (IncCon), line approximation, the control of ripple correlation (RCC), PID control, fuzzy logic control (FLC) [2], genetic algorithm [4], neural network and neuro-fuzzy approaches [5]. On the other hand, intelligent systems like FLC, neural network and genetic algorithms are able to determine their parameters, and are capable of operating under highly nonlinear system. In recent years, several techniques hybridizations seen the day like the ANFIS (Adaptive Network Fuzzy Inference System) [6]. Their power lies in the possibility of incorporating a knowledge base, dealing with imprecise data by fuzzy logic and introduce learning via the neurons of the network. The response time, overflow and static error criteria can be assured by conventional control techniques, while the robustness criterion remains a challenge for researchers. Hence, the FLC-based MPPT algorithm attracts many researchers. Freshly in literatures, several MPPT techniques using these techniques were suggested [2-5, 7, 8]. In comparison with P&O algorithm, they provide superior tracking performance.

To track the maximum power, point this paper proposes a comparison between a Fuzzy Logic Controller with reduced number of rules and ANFIS (Adaptive Network Fuzzy Inference System) controller, this control is imposed by the non-linear characteristics of the PV. Both methods use variation of the power ( $\Delta P_{pv}$ ) and current variation ( $\Delta I_{pv}$ ) as the inputs. Those two methods are tested in terms of steady state performance and the tracking time using MATLAB/Simulink.

## 2. MAXIMUM PERFORMANCE POINT TRACKER OPERATION PRINCIPLE

The connected load characteristics have an important influence on the photovoltaic operating behavior, shown in Figure 1 [9, 10]. For a resistive load, equals  $R_i$ , there is only one particular operating point where the optimal adaptation occurs, called the maximum power point (MPP) in our case noticed as  $P_{max}$ , shown in Figure 2. Therefore, if the load and the source are directly connected, it is rarely that the PV module operating point is optimal. To resolve this problematic, a use of an MPPT controller driving a DC–DC converter, between the source and the load, is necessary, illustrated in Figure 3 [11]. It is well known that with the temperature and the irradiance variation, the PV system characteristics and its MPP vary corresponding to a curve known as P–V curve, shown in Figure 4 and Figure 5 [12, 13]. Thus, to track this variation an MPPT controller has become essential. The last decade, many MPPT control techniques appeared [14, 15]. Classified as follow:

- a. Voltage flyback methods (compare the PV operating)
- b. PWM signal control generation by the voltage and a reference applied to the DC–DC converter [16].
- c. Current flyback methods (use the PV module)
- b. -Estimation the MPP current by the short circuit current flyback methods [17].

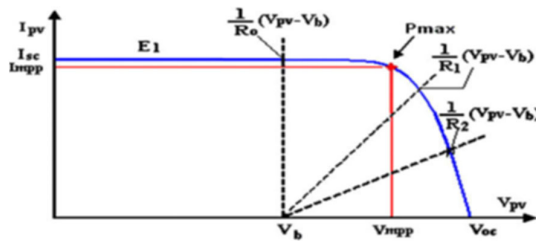


Figure 1. I-V characteristic of the PV module

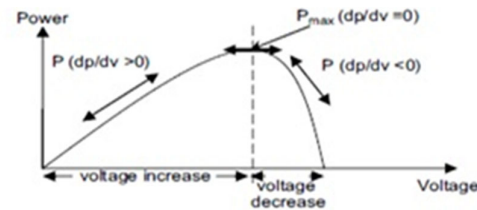


Figure 2. P-V characteristic of the PV module

## 3. DC-DC CONVERTER

In fact, The DC-DC converter is an adaptation between the PV panel and the load. This adaptation is provided by the act on the converter duty cycle (D) ensuring the maximum performance point coincides with the operating point [18]. Figure 4 illustrates the Boost converter, whose output voltage ( $V_b$ ) is greater or equal than the input voltage  $V_i$  (PV voltage generator) [17].

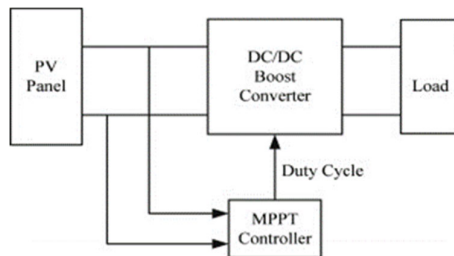


Figure 3. Photovoltaic system

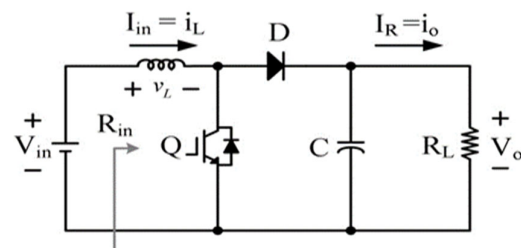


Figure 4. The DC-DC boost converter wiring

The DC-DC boost converter amplifies the voltage and decreases the current in order to maintain between its input and output a stable power. It is a class of SMPS (Switched-Mode Power Supply) containing minimum two semiconductors (a diode and a transistor) and at any rate one vitality stockpiling component: a

capacitor, inductor, or on the other hand the two in blend. To decrease voltage ripple, filters made of capacitors (some of the time in mix with inductors) are ordinarily added to such a converter's output (LSF) and input (supply-side filter) [19]. The boost converter can emerge out of any desirable DC sources, for example, batteries, photovoltaic panels, rectifiers and DC generators. A procedure that changes one DC voltage to a different DC voltage is called DC-to-DC conversion [17]. A boost converter is a DC-to-DC converter with a voltage above the voltage of the source. Sometimes a boost converter is called a step-up converter because the source voltage is "stepped up." Due to the need to conserve power ( $P = VI$ ), the source current is higher than the load current [20]. The used boost converter's dynamic model, shown in Figure 4.

#### 4. ANFIS (NEURO-FUZZY) MPPT CONTROLLER

ANFIS is a combination between fuzzy logics (FL) and the highly interconnected Artificial Neural Network (ANN). In fact, each layer of the ANN uses a function of the FL. The second layer uses the Membership function, the third one uses the rules the fourth one is the sum of the third layer nodes, the first and the fifth ones are the input and the output layers. ANFIS is the benefits of both types of machine learning (Fuzzy Logic and Neural Network) into single technique methods. The ANFIS toolbox constructs a fuzzy inference system (FIS) whose membership function parameters are modified using either a back-propagation algorithm or a combination of back propagation algorithm and the least square form of approach (Figure 5). This learning process is called the Hybrid Learning Technique. This enables fuzzy systems to learn from the data they model. ANFIS works by applying Neural Network Learning [21, 22]. ANFIS is known for its remarkable power of, nonlinear mapping, modelling, pattern recognition, and learning [23].

In this paper, the two ANFIS inputs, shown in Figure 6 are:  $a$  and  $b$ , and the single output is  $c$ . the Sugeno fuzzy model, a typical for the rule is set with the fuzzy if-then rules as

Rule: If  $x$  is  $X$  and  $Y$  is  $B$ , then  $c = (p*a + q*b + z)$ .

Where  $X_i$  and  $B_i$  are the fuzzy sets in the antecedent, and  $p$ ,  $q$  and other parameters are determined during the training process. ANFIS involves five layers, and each layer's nodes depend on the number of inputs, membership function and rules and mostly on a single output. The MATLAB program includes an ANFIS tool used to build the FLC controller, this system utilizes the process of training the ANFIS based on the training data. This data contains vector of the inputs representing the operation temperature and the operation solar irradiation, and as output, the vector that represents the best decision of duty cycle given to the system to run at MPP, illustrated in Figure 7.

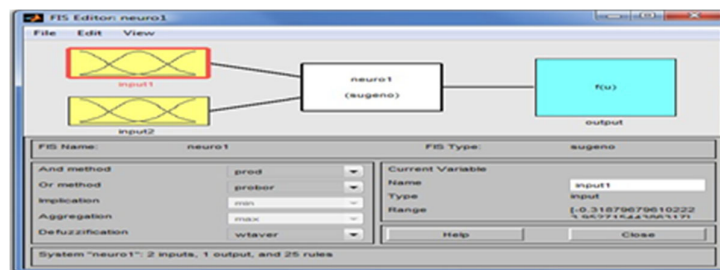


Figure 5. Matlab ANFIS toolbox

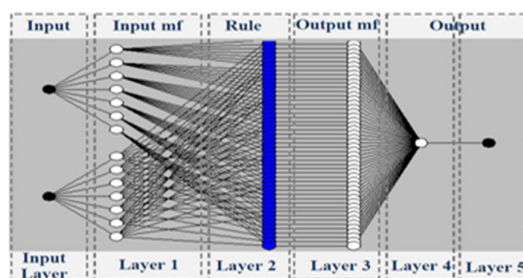


Figure 6. Detailed anfis matlab structure

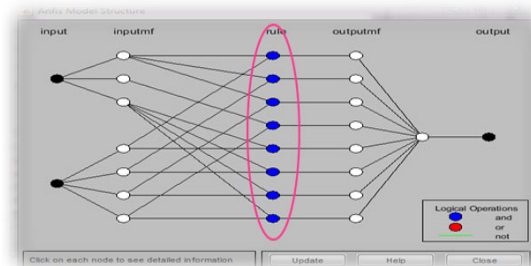


Figure 7. Anfis model

## 5. FUZZY LOGIC MPPT CONTROLLER

In many new literatures, the fuzzy logic based MPPT command has been used; this robust command does not necessitate exact knowledge of a mathematical system model. The developer, on the other hand, requires complete knowledge of the function of the PV system. The inputs of the theoretical MPPT controller in this paper are the power variance ( $\Delta P_{pv}$ ) and the current variation ( $\Delta I_{pv}$ ). Influence of the solar radiation for constant temperature is shown in Figure 8. Figure 9 shows the MFs of the input and output variables used for the proposed controller. In Figure 10. The MFs of the input variables; both  $\Delta P_{pv}$  and  $\Delta I_{pv}$  are in triangular form Figure 9. The MF of the output (duty cycle step size D), which is also in triangular form Figure 10. In Figure 9, DP means the power variation, DI (current variation) and D (duty cycle variation). The linguistic variables are: P (positive), N (negative), B (big), S (small) and Z (zero). from Figure 9, each of the input variables  $\Delta P_{pv}$  and  $\Delta I_{pv}$  are mapped into five different linguistic values. Instead of usual proposed fuzzy system, our model is set with a limited number of rules [17].

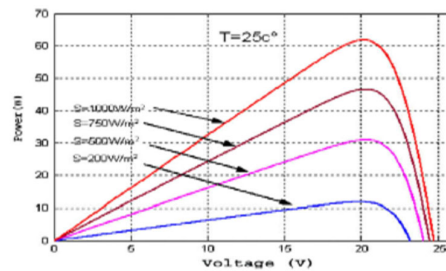


Figure 8. Influence of the solar radiation for constant temperature

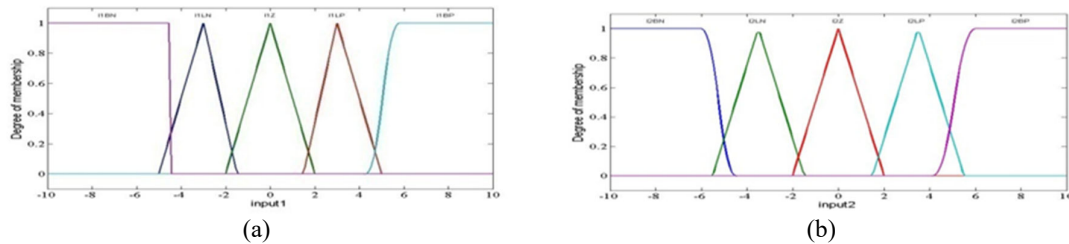


Figure 9. Membership functions for inputs (a) input1 DPv, (b) input2 DIv

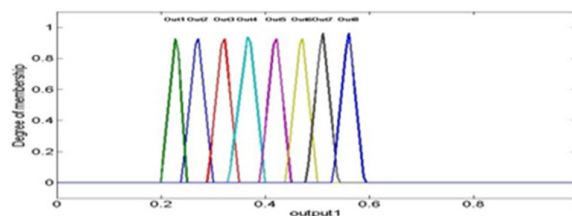


Figure 10. Membership function for output D (duty cycle)

The fuzzy inference uses Mamdani's method. The fuzzy controller structure is shown in figure 11, Table 1, and the defuzzification uses the centre of gravity to calculate the duty cycle, the FLC output, the Table 1 below indicates the control rules.

Table 1. Controller rules					
	NB	NS	Z	PS	PB
NB	BP				
NS	PS				
Z		Z	Z		
PS			NS	NS	
PB				NB	Z

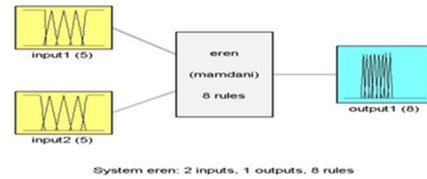


Figure 11. The fuzzy controller structures

## 6. IMPLEMENTATION AND RESULTS

### 6.1. Implementation

The proposed FLC and the ANFIS controller have been realised and tested under SIMULINK (MATLAB) to a 100-kW Grid-Connected PV Array, shown in Figure 12 (Detailed Model). In this work, changes in solar radiation are applied to assess and check the robustness of the proposed controller [24]. Irradiation pattern is shown in Figure 13 [17], for the PV the model is the SUNPOWER SPR-305-WHT

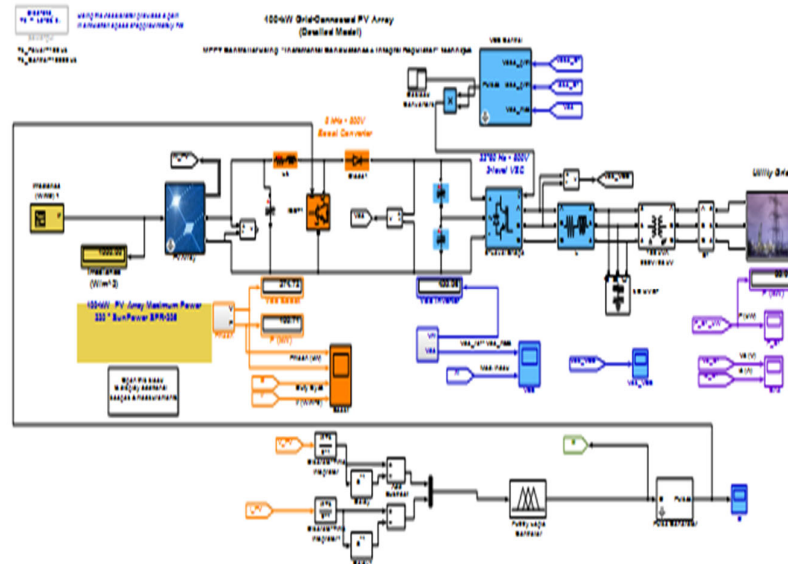


Figure 12. 100-kW Grid-connected PV Array

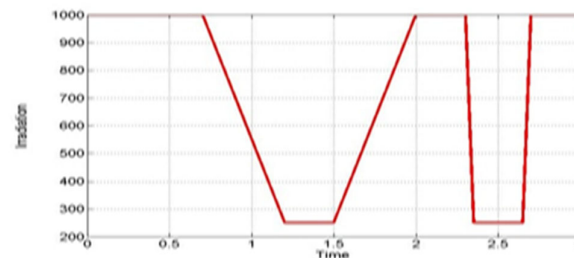


Figure 13. Irradiation pattern

### 6.2. Results

The simulation results for FLC and ANFIS are respectively shown in figures below. Generator output power, shown Figure 14 and Figure 15, operating voltage shows in Figure 16 and Figure 17, operating

*Comparison between proposed fuzzy logic and ANFIS for MPPT control for ... (Lotfi Farah)*

current shown in Figure 18 and Figure 19, and the duty ratio shown in Figure 20 and Figure 21 and grid voltage illustrated in Figure 22 and Figure 23. Using a boost converter under standard test conditions has shown that the proposed FLC controller shows better static error, shown in Figure 25 (1.62 kW so  $1.62/100.71 = 0.016\%$ ) [17] and less Tracking time error illustrated in Figure 24 (less than 0.005s) comparing to the ANFIS controller (1.85 kW so  $1.85/100.71 = 0.020\%$  static error and 0.011s for Tracking time) in Figure 25.

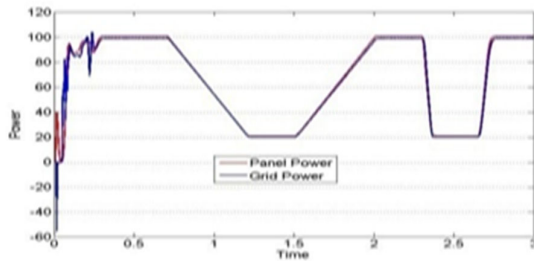


Figure 14. FLC generator output power

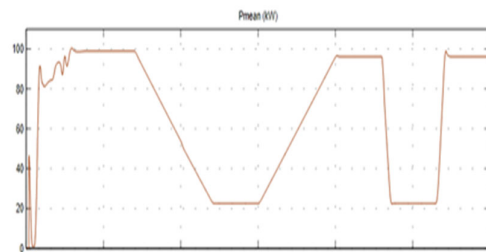


Figure 15. ANFIS panel output power

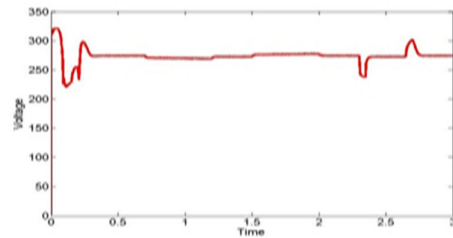


Figure 16. FLC operating voltage

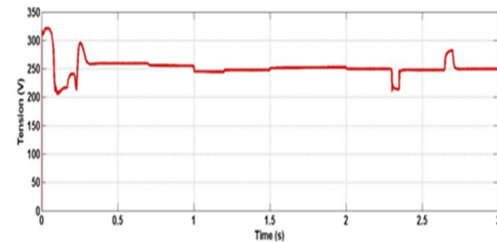


Figure 17. ANFIS operating voltage

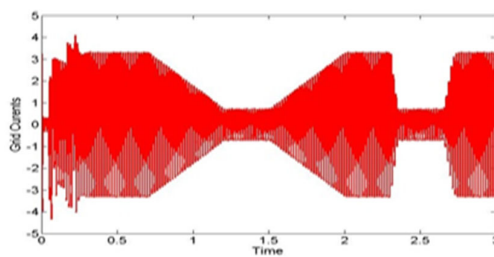


Figure 18. FLC grid currents

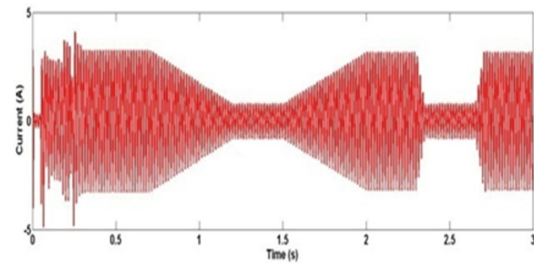


Figure 19. ANFIS grid currents

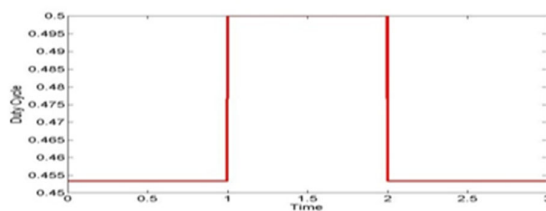


Figure 20. FLC duty cycle

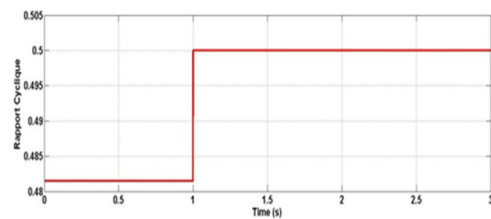


Figure 21. ANFIS duty cycle



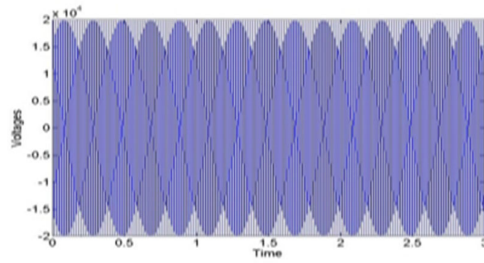


Figure 22. FLC grid voltage

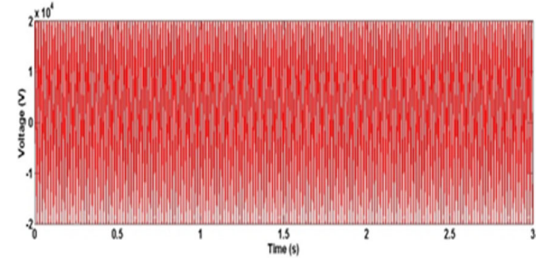
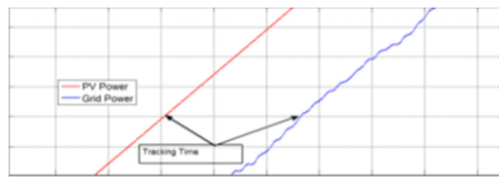
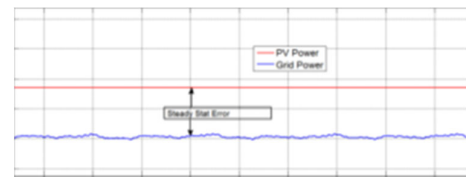


Figure 23. ANFIS grid voltage



(a)



(b)

Figure.24 (a) tracking time calculation method (b) steady state error calculation method

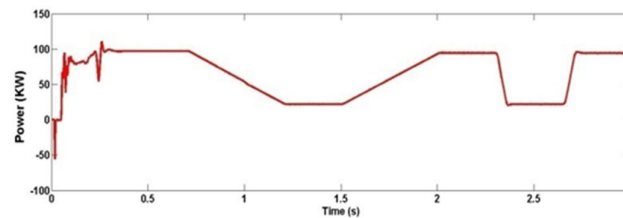


Figure 25. ANFIS grid power output

Table 2. Comparison between used methods and P&amp;O

Technique	Vitesse de poursuite	Erreur statique
P&O	0.015 s	0.74%
FLC WithreducedRules	0.005 s	0.016%
ANFIS	0.011 s	0.020%

## 7. CONCLUSION

In this paper, an FLC with reduced number of rules based MPPT and ANFIS based MPPT have been developed and tested in MATLAB/Simulink environment, based on the simulation it can be concluded that with the both controllers the PV panel can deliver the maximum power. However, the performance of fuzzy with reduced rules MPPT is better than ANFIS based MPPT in terms of tracking speed and static error due to its reduced number of rules (8) instead of conventional (25) which makes it's lighter and improve global performance.

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