

Experimental installation of wireless power transfer system based on the series resonance technology

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ABSTRACT

In this work, we aim to install a wireless power transfer (WPT) system experimentally. Series resonance technology was used to achieve zero-voltage switching (ZVS). We investigated the impact of the primary and secondary resonance frequencies (f_p and f_d), and inverter frequency switching (f_{ch}) on the efficiency (β) and maximum transfer power in a WPT system based on the inductive wireless power transfer (IWPT) technology. An ultrasonic device was utilized as a generator to excite the coil at the primary side. The experimental outcomes showed that there is an optimum unlike f_p and f_d can be got to match f_{ch} . It was found also that there is a trade-off between the power supplied to the load (PRL) and DC-DC efficiency (β). At an air-gap of 5 cm, the obtained results are recorded as follows; the peak recorded system β is 62% that was obtained at $f_p=19$ kHz, $f_d=f_{ch}=24$ kHz that is corresponding to 101.88W of PRL; whereas the highest PRL resulted i.e. 244W when $f_p=19$ kHz, $f_d=24$ kHz, $f_{ch}=21$ kHz at 61% of β ; in such case, the maximum β * PRL multiplication was achieved i.e. 149. Moreover, the coils' misalignment was studied. The outcomes showed that the lateral misalignment has worst effect on the PRL and β than the air-gap. The experimental results were validated with simulation ones.

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1. INTRODUCTION

The interest in the wireless power transfer (WPT) technique has considerably increased in recent few years, because of the safety and conveniences over the wired charging technology. In general, the WPT technology for electric vehicles (EVs) and smartphones battery charging includes inductive and capacitive wireless power transfer (IWPT and CWPT) [1-5].

In this work, only the IWPT technique is presented, where the power transmits from the primary coil to the secondary one electromagnetically. The coupling interface surface area between the coils and air-gap are parameters impacting the coupling factor (k). This parameter has an effect on the whole system's efficiency and performance. The air-gap between the coils is the most challenging factor. As the air-gap rises, the magnetizing current, leakage inductance, and input VA rating rise accordingly. Consequently, the system cost increases, system efficiency diminishes due to losses increasing [6-8].

A resonance circuit technique has been utilized to enhance the IWPT system efficiency and performance [2, 9]. The resonance circuit is nothing but capacitor(s) linked with the coils in series/parallel to compensate its inductance. At the primary side, the resonance circuit minimizes reactive power, improves the

power factor, less VA ratings which result in less voltage stress on the system's components of the system, and low inverter cost. At the secondary side, the resonance circuit improves the system efficiency and maximizes the power delivered to the battery. For the EVs applications, the normally utilized inverter switching frequency within the range of 10-200 kHz. The switching frequency is mainly based on the air-gap and coils' size. The high-quality factor of the coils results in high power transmission efficiency [6, 10, 11].

However, to make the most of resonance technology, the resonance frequency at the primary (f_p) should be correlated with the resonance frequency at the secondary (f_d) side; and both f_p and f_d should be correlated with the inverter switching frequency (f_{ch}) to achieve zero-voltage switching (ZVS). Recently, in [2, 12, 13], in a bid to achieve the highest power transfer level, the f_p and f_d were set to be equal to the f_{ch} . While in [14], it was found that at f_{ch} equal to the f_d , the maximum power transfer efficiency was achieved [14]. It was proven that the transmitted power is not constantly an optimum at resonance case [15]. The power transfer level is mainly based on the coupled coils' inductance and its quality factor, switching frequency, the square of input current and mutual inductance. However, there is no interest has given to discover an optimum f_{ch} , f_p , and f_d to accomplish the highest power transfer level and efficiency [16, 17]. In this work, the impact of various f_{ch} , f_p , and f_d on the IWPT level and efficiency was studied; to get resonance circuits, resonance capacitors were utilised to adjust f_p and f_d . This aims to accomplish a maximum WPT efficiency and load power by discovering an optimum f_{ch} , f_p , and f_d . Moreover, since the the coupled coils misalignment is a common problem in the IWPT systems, we carried out a study to impact of this issue on the DC-DC system efficiency (β) and resistive load power (PL).

The transferred power and efficiency in a WPT system basically rely on the resonance frequency [18, 19], magnetic coupling factor, k , and mutual inductance, M , which are mainly based on the coil configurations and varied with the air-gap (d) and coils' misalignment [18-20]. In this work, the spiral coil configuration of copper wires was built experimentally to deliver power wirelessly to a resistive load through an air-gap of 5 cm. The misalignment issue was investigated as well.

The next sections of the paper are arranged as follows: Section 2 presents the WPT system, which includes the experimental setup, mathematical model as well as the considered coil configuration and misalignment between the inductively coupled coils. Section 3 explains the methodology used to implement the experimental work and how the data are collected. Section 4 illustrates the experimental outcomes and discussion. Section 5 presents the conclusion.

2. INDUCTIVE WIRELESS POWER TRANSFER SYSTEM

As mentioned earlier, the d between the coupled coils is playing a major role in any IWPT system performance. The self-inductances of the primary and secondary (L_1 and L_2) coils, k and M are parameters utilized to describe the inductive coupler; The relation between these parameters is expressed in (1) [20].

$$M = k\sqrt{L_1L_2} \quad (1)$$

2.1. Experimental Setup

The adapted IWPT system includes an ultrasonic generator (see technical characteristics in Table) that was utilized to excite the primary coil; based on it favorable features among other topologies, the series-series (SS) resonance technology was utilized [2]. The experimental setup of the presented IWPT system is depicted in Figure 1. Where C_{p1} , C_{p2} , R_1 , and R_2 , are the equivalent parallel capacitances and the equivalent series resistances, respectively. From Figure 1, it can be noted that the ultrasonic generator includes the followings components:

- Generator unit,
- Remotely controlled panel which used for parameterization,
- Adapter which is used for external control;
- A half-bridge inverter which is made from IGBT transistors

The f_{ch} is controlled by utilizing the handheld control unit which linked through RS485-232 adapter to the generator unit. The ultrasonic generator's technical characteristics are mentioned in Table 1 [21]. However, due to its most robust to the rotation misalignment and uniform flex distribution, the spiral configuration was adapted to create the coils:

- The copper wire coils;
- Capacitors (WIMA type) were utilized for the SS resonance technology, the f_p and f_d are calculated theoretically as in equation (2).
- A full-bridge rectifier made of four power diodes of type Schottky (DSS 2x61-01 A). To soak up the generated heat and wasted it. The rectifier mounted over the heatsink with dimension 20x12.5x2.5 cm.

- A filter capacitor (2200 μF) linked parallelly to load (i.e. resistive) to supply it with a pure DC power.

$$f_p = \frac{1}{2\pi\sqrt{L_1C_1}}, f_d = \frac{1}{2\pi\sqrt{L_2C_2}} \tag{2}$$

Table 1. The ultrasonic generator’s characteristics for the MSG.1200.IX.LF model [21].

Device elements	Specifications
Weight	10 kg
Dimensions (h x w x d)	250 mm x 150 mm x 450 mm
Supply Voltage and frequency	230/220V (50 Hz)
Input Power (Max)	700 W
Output HF Voltage	500 V-rms
Average Output Power (continuous)	600 W
Max. pulsed power (Peak Output)	3000 W
Inverter frequency	17.5-28 kHz

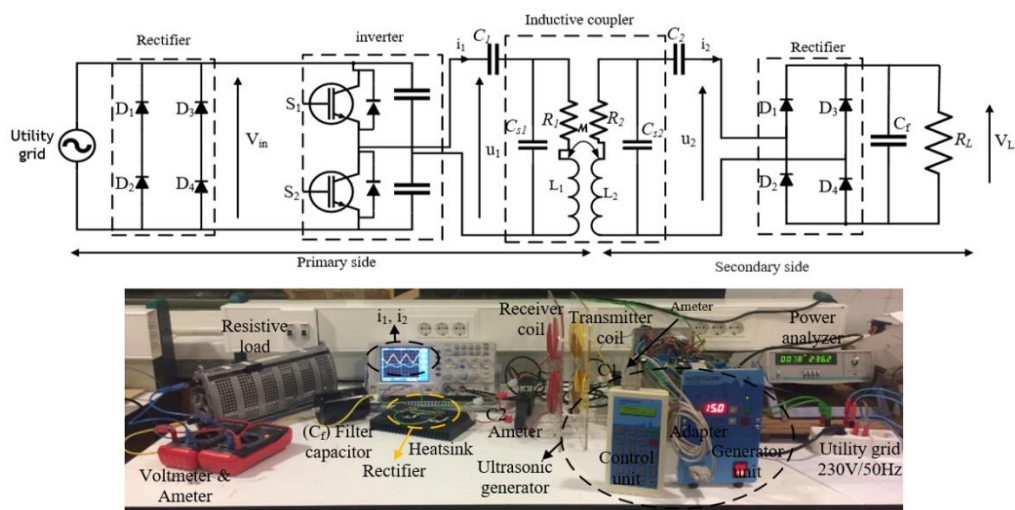


Figure 1. Experimental setup of IWPT system

2.2. Mathematical model

To validate the empirical outcomes with the theoretical ones, the mathematical IWPT system model is presented here. The dependent voltage source was used to model the inductive coupler, the equivalent circuit of the IWPT system that mentions in section 2.1 is shown in Figure 2, where the output of the ultrasonic generator is modeled as a square voltage source with an RMS value of (u₁).

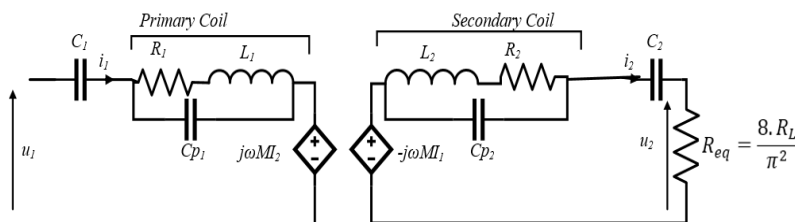


Figure 1. The equipollent model based on the adapted IWPT system

The equivalent primary impedance (Z_p), secondary impedance (Z_s), reflected impedance from secondary to the primary (Z_r), and input impedance (Z_{in}) are expressed in equations (3), (4), (5), and (6), respectively; the effect of the Cp1 and Cp2 are neglected due to their small values compare with other parameters values.

$$Z_p = R_1 + j\omega_{ch}L_1 + \frac{1}{j\omega_{ch}(C_1)} \quad (3)$$

$$Z_s = R_2 + j\omega_{ch}L_2 + \frac{1}{j\omega_s(C_2)} \quad (4)$$

$$Z_r = \frac{M^2\omega_{ch}^2}{Z_2} \quad (5)$$

$$Z_{in} = Z_p + Z_r = Z_p + \frac{\omega_{ch}^2 M^2}{Z_s} \quad (6)$$

Based on Figure 2, the expression of the RMS input current at the primary circuit i_1 and RMS secondary current i_2 are described in equations (7) and (8), respectively.

$$i_1 = \frac{u_1}{|Z_{in}|} \quad (7)$$

$$i_2 = \frac{|-j\omega M u_1|}{|Z_p Z_s + \omega_{ch}^2 M^2|} \quad (8)$$

From equations (7) and (8), the voltage gain (G_v) can be written as;

$$|G_v| = \frac{u_2}{u_1} = \frac{i_2 R_{eq}}{i_1 Z_{in}} = \frac{|-j\omega_{ch} M R_{eq}|}{|Z_p Z_s + \omega_{ch}^2 M^2|} \quad (9)$$

However, the DC load power (P_{RL}) which delivered to load is described as follows;

$$P_L = \frac{u_2^2}{R_{eq}} = i_2^2 \cdot R_{eq} \quad (10)$$

2.3. Inductively coupled coils

Generally, the k is utilized to predict the IWPT performance [2, 10, 11]; The DC-DC efficiency can be computed as follows;

$$\beta = \frac{P_L}{P_{in}} \quad (11)$$

where the input DC power (P_{in}) was calculated using approximation formula:

$$P_{in} = \text{the input power (AC) – no-load losses (i.e. ultrasonic generator)} \quad (12)$$

In this work, the well-aligned coils, as shown in Figure 3(a), air-gap fluctuation as well as the lateral misalignment, Figure 3(b), with $L > 0$ between the coils were investigated.

Based on the equation (13), the k was measured experimentally as follows,

- A function generator with a set voltage of V_1 was utilized to energize the primary coil;
- Utilizing an oscilloscope, the induced EMF (V_2) was measured at the secondary coil.

$$k = \frac{V_2}{V_1} \quad (13)$$

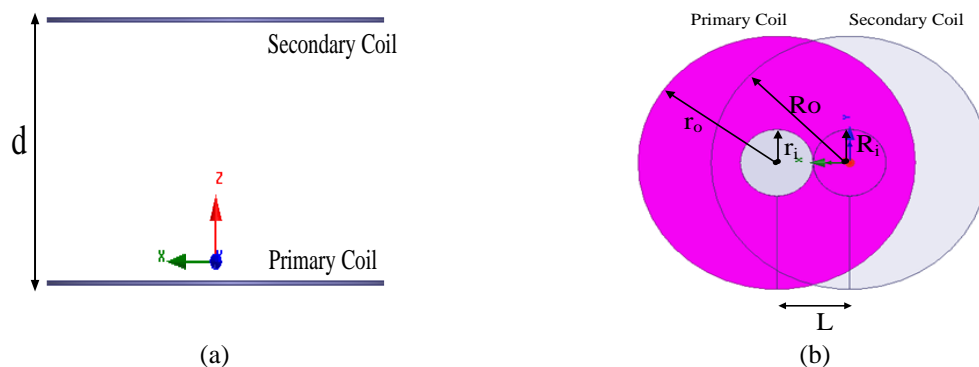


Figure 3. Inductively Coupled Coils, (a) well-alignment coils (b) coupled coils with lateral misalignment (L)

3. MATERIALS AND METHODS

In this paper, an IWPT system was implemented experimentally. This work involves the study of the impact of the f_{ch} , f_p , and f_d on the P_{RL} & β and investigate the optimum $\beta \cdot P_{RL}$ condition. The f_{ch} is controlled using the ultrasonic generator's control unit. The f_p and f_d were controlled utilizing the resonance capacitors that are connected in parallel and/or series to obtain the desired resonant frequency. Based on the frequency characteristics, the f_p and f_d were computed utilizing the LCR HiTESTER of model HIOKI 3532-50.

The power analyzer connects the ultrasonic device to the 230 V/50 Hz of electricity plug. The function of the power analyzer is to compute the AC input electric power. The ultrasonic device's no-load losses were gauged; these losses were assumed to be the same at all loading conditions; this presumption was utilized to compute the input DC power (equation (12)).

A spiral shape was considered to constitute the coils:

- The length each copper coil wire is 17 m,
- The cross-section area of the copper wire is 1.5 mm^2 ,
- $r_i=R_i=2.5 \text{ cm}$, $r_o=R_o=11.88 \text{ cm}$ with 2 mm of coil pitch, and
- The turns number of the coils is the same i.e. 34.

Utilizing digital RLC meter, the coils' parameters were determined.

Several experiments were carried out at well-alignment coils at $d=5\text{cm}$ with various f_p , f_d , and f_{ch} ; the β was identified accordingly at each situation. Moreover, the impact of the d and L on the P_{RL} was researched. It was presented a case to research the effect of f_{ch} on P_{RL} . The imperial data were validated with the theoretical ones that was obtained based on the mathematical model implemented in MATLAB.

4. EXPERIMENTAL OUTCOMES AND DISCUSSION

This section shows the experimental outcomes which include the parameters of the coils and adjusting f_{ch} , f_p , and f_d to achieve an optimum β and P_{RL} . Based on the ultrasonic generator's technical characteristics (Table), only 15% of the device power was utilized with no-load losses 18W.

4.1. Coils parameters

The coils' resistance, inductance, and quality factor were determined experimentally by utilizing the digital RLC meter as shown in Table 2. The f_p and f_d were calculated utilizing the frequency characteristics in order to take into account the coils' distributed capacitances. The obtained outcomes showed that

- When the coil connected in series with a capacitor of $0.47 \mu\text{F}$, f_p and f_d are about 19 kHz.
- Two parallel capacitors of $0.15 \mu\text{F}$ are linked in series with a coil, that gives a f_p and f_d are about 24 kHz.
- Three parallel capacitors of $0.15 \mu\text{F}$ are linked in series with a coil, that gives an f_p and f_d about 28 kHz.

Table 1. Experimental measured parameters of the coupled coils at 1 kHz.

Parameter	Primary coil	Secondary coil
$L_{1,2} (\mu\text{H})$	148.2	151
$R_{1,2} (\Omega)$	0.446	0.474
$Q_{1,2}$	2.13	2.02
k		0.42
$M (\mu\text{H})$ at $d=5 \text{ cm}$		62.82

4.2. Resonance

As mentioned in section 4.1, the f_p and f_d were regulated utilizing resonance capacitors. The of L_1 and L_2 at 1 kHz were assumed to have constant values at higher frequencies when the f_p and f_d computed. Therefore, for various f_{ch} , at $R_L=32 \Omega$, $d=5 \text{ cm}$, the impact of the f_p and f_d on the β was investigated, the outcomes are shown in Figure 4. As can be observed from Figure 4, the maximum achieved β at f_{ch} of 28 kHz is 62% (at this efficiency the obtained P_{RL} is 101.8 W) that was achieved at $f_p=19 \text{ kHz}$, $f_d=24 \text{ kHz}$. The next highest β i.e. 61% was obtained at $f_p=19 \text{ kHz}$, $f_d=24 \text{ kHz}$, and $f_{ch}=21 \text{ kHz}$ (at this efficiency the obtained P_{RL} is 244.13 W). Based on the obtained results, the maximum β values were occurred at $f_d \approx f_{ch}$. At this condition, the power reflected from the secondary side to the primary side removed. The obtained outcomes are correlated with the ones presented in [14]. The maximum achievable P_{RL} is 244.13 W was obtained at $f_{ch} > f_p$. At this condition, the ZVS occur since the inverter inductively loaded; this makes the losses of the half-bridge inverter are near to zero [14, 24].

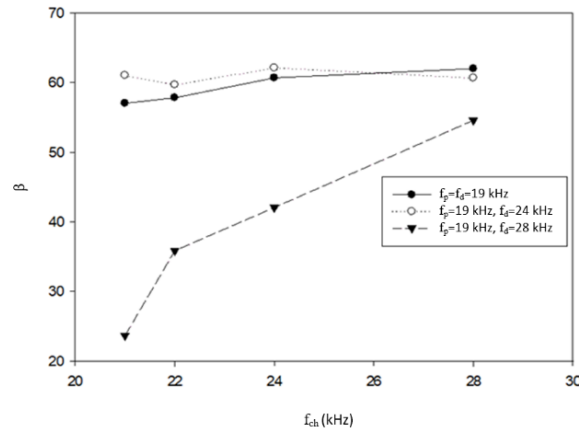


Figure 4. β against f_{ch} for various f_p and f_d

As it is known, high β with P_{RL} is an eligible outcome. Therefore, the optimum $\beta \cdot P_{RL}$ factor was studied. The obtained outcomes as shown in Figure 4 indicate that the peak value i.e. 149 ($P_{RL} \approx 244$ W & $\beta \approx 61\%$) accomplished at $f_p = 19$ kHz, $f_d = 24$ kHz, and $f_{ch} = 21$ kHz where $f_d \approx f_{ch}$. The slight difference between f_{ch} and f_d because the resistive load made of copper wire that has a small inductance which effects the f_d value. In other words, according to equation (2), the real f_d is a bit below than 24 kHz i.e. $f_{ch} \approx f_d$; where at this condition zero (or very slight amount) reflected power obtained.

The frequency characteristics behavior of P_{RL} and P_{in} are analogous. Therefore, only the P_{RL} is presented here. At $f_p = 19$ kHz, $f_d = 24$ kHz condition (peak $\beta \cdot P_{RL}$), the impact of the f_{ch} on the P_L was investigated imperically when $d = 5$ cm, $P_{RL} = 32$ Ω ; the measure u_1 experiment values were used in the IWPT system's mathematical model to compute the P_L for validation purpose, the outcomes are shown in Figure 5.

As can be seen, Figure 5, the P_{RL} declines considerably as the f_{ch} rise; for each situation, the peak P_{RL} was resulted when f_p a bit less than f_{ch} . The difference between the experimental and simulation curves due to the losses of the ultrasonic generator which is not considered in the mathematical model.

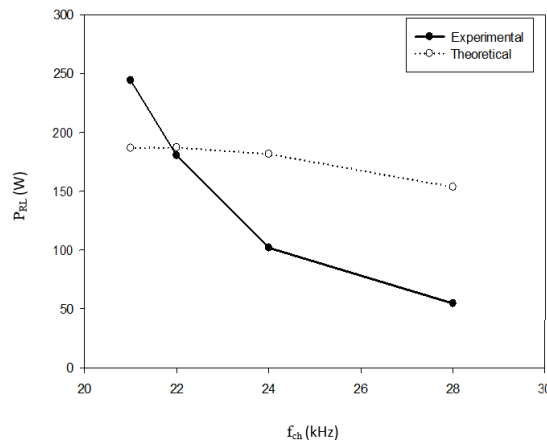
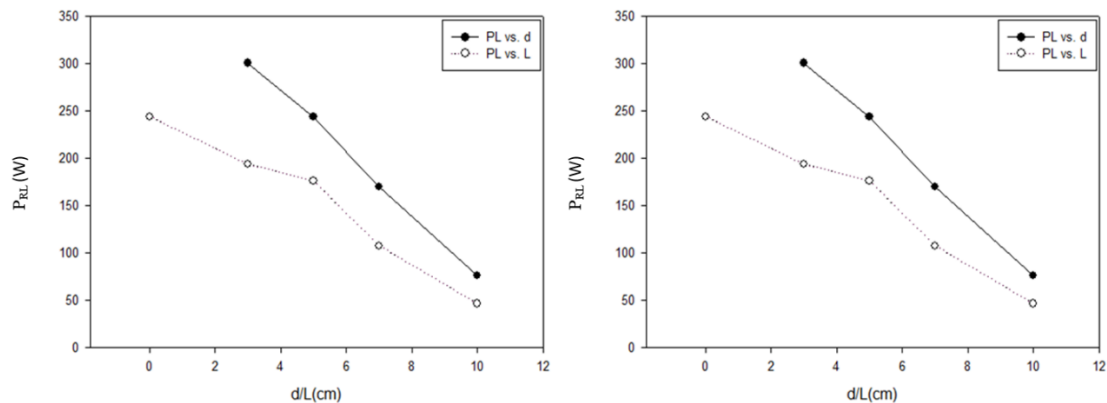


Figure 5. P_{RL} against f_{ch} at $f_p = 19$ kHz, $f_d = 24$ kHz

4.3. Misalignment

At peak $\beta \cdot P_{RL}$ situation i.e. $f_p = 19$ kHz, $f_d = 24$ kHz, $f_{ch} = 21$ kHz, the air-gap and lateral misalignment variations impact on the P_{RL} were researched; the outcomes are illustrated in Figure 6. As can be noted, Figure 6, the two curves have same behavior; where, as the d rises the P_{RL} sharply get down. Similarly, as the L rises the P_{RL} considerably decreases. However, to supply a fixed power of good quality and high efficiency the misalignment should be avoided. A mechanic or magnetic trap have been used by some IWPT systems to avoid the misalignment [25].

Figure 6. P_{RL} versus d and L at $d=5$ cm

5. CONCLUSION

This work has researched the impact of the f_{ch} , f_p , and f_d in an IWPT system on the P_{RL} and β . The outcomes proved an optimum f_p , f_d , and f_{ch} values are exist to achieve peak reachable β . Meanwhile, there are other f_p , f_d , and f_{ch} values to achieve peak reachable P_{RL} . The imperical outcomes determined that f_{ch} and f_d should have same values (or almost equal) with $f_{ch} > f_d$ and both should be a bit more than f_p to achieve peak $\beta * P_{RL}$. The most we can talk about that these results highlight the enhancements in our work by studying the best f_p and f_d values to be tuned with the f_{ch} as well as regulate the f_p and f_d in a bit to improve the $\beta * P_{RL}$ factor. The ultrasonic device with adjustable f_{ch} has utilized in the primary side to supply its coil; while the f_p and f_d have been regulated by utilizing resonance capacitors. However, some ultrasonic generator limitations are worthy of note that the f_{ch} cannot exceed the limit (17.5-28 kHz). The coils' misalignment has been researched as well; the outcomes identified that as the d has a more negative impact on P_{RL} than L . However, the future work should include a study of higher frequency ranges, for example, 120 kHz.

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