

# High-efficiency two-stage LED driver with integrated PFC and LLC resonant converter for public lighting

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## ABSTRACT

This paper presents the design, implementation, and experimental validation of a 150 W two-stage light-emitting diode (LED) driver integrating a power factor correction (PFC) stage and a half-bridge LLC resonant converter for public lighting applications. The problem addressed is the insufficient power quality, limited efficiency, and poor harmonic performance of conventional LED drivers used in street lighting. The proposed method combines an advanced PFC front-end with an LLC resonant converter optimized using first harmonic approximation (FHA) to achieve high efficiency, stable output regulation, and soft-switching operation. Experimental results demonstrate a significant improvement in power quality, with the input current total harmonic distortion (THD) reduced from 134% to 17%, a near-unity power factor, a regulated LED output of 31.6 V/4.72 A, and a conversion efficiency exceeding 95%. The significance of this work lies in providing a high-performance, standards-compliant driver that supports reliable, energy-efficient, and grid-friendly public lighting with reduced operational costs.

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## 1. INTRODUCTION

Light-emitting diode (LED)-based street lighting has become the predominant choice in modern urban infrastructures due to its high energy efficiency, long lifetime, rapid switching capability, and compact design flexibility [1]–[5]. These advantages make LEDs especially suitable for large-scale public lighting systems, where reliability, energy savings, and low maintenance costs are essential [6]–[11]. To fully exploit these benefits, the associated LED driver must deliver stable and well-regulated power while maintaining high energy efficiency and compliance with international power quality standards. Despite significant progress in power electronics, many existing LED drivers still suffer from limitations such as insufficient power factor correction, elevated total harmonic distortion (THD), and reduced efficiency under varying load conditions [12], [13]. Switch-mode power supplies remain the preferred solution for LED applications due to their balance of efficiency and compactness, but they require careful design and optimization to ensure long-term reliability, controlled energy consumption, and high-quality illumination [14], [15].

Although numerous studies focus separately on improving power factor correction (PFC) circuits or refining resonant topologies, few works integrate an advanced PFC stage with a half-bridge LLC resonant converter specifically tailored to public lighting and validated through experimental prototypes [16]. This combined approach is rarely addressed in the literature, particularly when considering real operating conditions and compliance with harmonic and electromagnetic standards such as IEC 61000-3-2 and EN 55015 [17], [18]. To address these gaps, this paper introduces a 150 W two-stage LED driver that combines a high-performance PFC front-end with an optimized LLC resonant converter designed for soft switching, low harmonic distortion, and high efficiency. The design methodology includes analytical modeling of the resonant tank using the first harmonic approximation (FHA) and a detailed component sizing strategy [19]-[25]. Experimental evaluation of the developed prototype demonstrates stable LED current regulation, an efficiency exceeding 95%, and a reduction of input current THD from 134% to 17%. These results highlight the potential of the proposed architecture to meet international standards while supporting reliable, energy-efficient, and sustainable public lighting infrastructures [26].

## 2. METHOD

### 2.1. Project specifications

For this application, the main design objectives for the power converter are low cost, high-energy efficiency, and a wide operating range. The proposed 150 W LED driver adopts a two-stage architecture with five levels of power conversion, enabling an efficient distribution of functional blocks. The first stage is responsible for generating a regulated DC voltage while providing PFC. The second stage is based on an LLC resonant converter, powered by a half-bridge inverter, which efficiently drives the LED load.

Unlike conventional PWM DC-DC converters, which are generally characterized by limited efficiency due to the lack of galvanic isolation and precise current control, the half-bridge LLC topology offers superior LED current regulation and significantly higher efficiency. Moreover, this approach helps reduce the cost and size of the LED driver system. Compared to the LCC topology, the LLC topology provides better energy efficiency thanks to its lower switching losses and its ability to operate in resonant mode over a wider load range. While the LCC topology can achieve stricter voltage regulation, it often results in higher control complexity and greater losses at light load. Therefore, the LLC topology represents an optimal compromise between performance, efficiency, and implementation simplicity, making it particularly well-suited for high-efficiency LED driver applications. The LED driver we propose is based on a two-stage architecture, comprising a resonant LLC converter and a PFC stage, as illustrated in Figure 1.

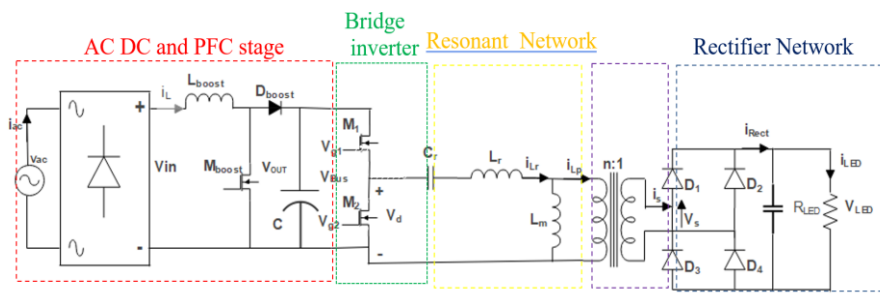


Figure 1. The proposed LED driver is based on an LLC resonant converter

### 2.2. Justification for selecting the half-bridge LLC topology

The converter selected for output current regulation is based on the LLC resonant topology, as illustrated in Figure 2. It consists of two power switches (M1 and M2), a series capacitor ( $C_r$ ), a series inductor ( $L_r$ ), a parallel inductor ( $L_m$ ), an optional transformer, a full-bridge rectification stage (D1, D2, D3, D4), and an output filter capacitor ( $C_o$ ).

The main advantage of the LLC resonant topology lies in its ability to achieve zero-voltage switching (ZVS) for the switching devices M1 and M2 over the entire operating range. Unlike the series resonant converter, the LLC converter can operate efficiently under light-load conditions by increasing the switching frequency. In this case, the impedance of the parallel inductor  $L_m$  increases proportionally with frequency, which prevents an increase in circulating current under light loads a common drawback in conventional parallel resonant topologies.

As previously mentioned, the LLC resonant topology combines the benefits of both series and parallel resonant circuits while eliminating their respective limitations. It supports a wide load range, while

maintaining a limited switching frequency variation and minimizing circulating current within the resonant tank. Moreover, the LLC converter provides multiple degrees of design flexibility, making it highly adaptable to specific application requirements. Its design is further simplified by the use of the FHA method, which facilitates accurate modeling and optimization.

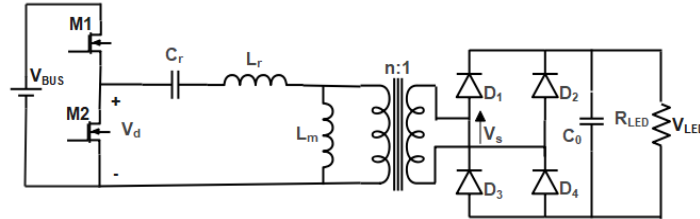


Figure 2. Second stage of the proposed LLC-Type LED driver

**2.3. Operating principle of the LLC resonant topology**

The analysis of the LLC resonant converter is significantly simplified by applying the FHA of the square waveforms. The LLC resonant tank acts as a filter, attenuating the higher-order harmonics of the square-wave voltage supplied by the inverter. As a result, the output power is primarily transferred through the fundamental frequency component of the waveform. This approximation is applied directly to the input voltage, which is a square wave generated by switches M1 and M2 from a DC source. The square waveform is then approximated as a sinusoidal waveform at the same fundamental frequency for the purpose of analysis and design.

**2.4. Input voltage characteristics**

The input voltage to the LLC converter, denoted as  $V_{Bus}$ , is the regulated DC voltage provided by the first stage. The switches M1 and M2 operate at a 50% duty cycle, with a  $180^\circ$  phase shift between them, producing a square-wave voltage oscillating between 0 V and  $V_{Bus}$ . The DC component, equal to  $V_{Bus} / 2$ , is blocked by the series capacitor  $C_r$ , resulting in an AC waveform centered at 0 V, swinging between  $-V_{Bus} / 2$  and  $+V_{Bus} / 2$ , as illustrated in Figure 3. The corresponding sinusoidal voltage at the output of the resonant tank, derived under the First Harmonic Approximation, is denoted as  $V_{dFHA}$ , and is also shown in Figure 3.

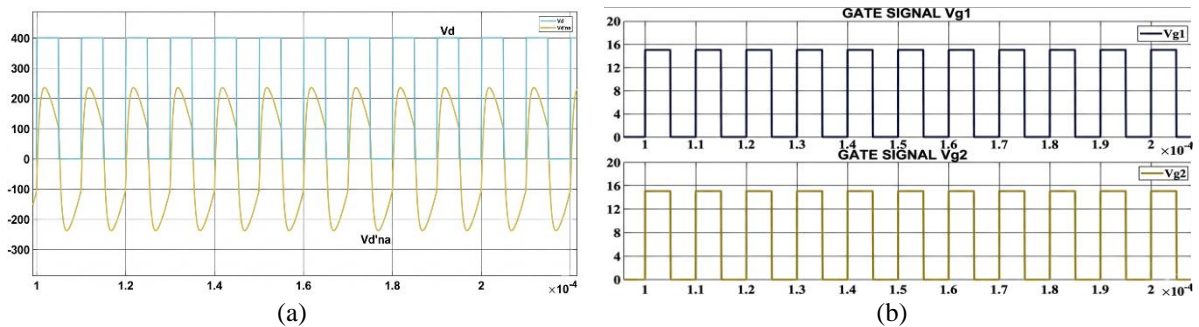


Figure 3. Simulation results for the system: (a) output voltage waveform generated by switches M1 and M2 and (b) simulated gate-drive signal

The harmonics of the voltage at the output of the half-bridge inverter are filtered by the resonant tank composed of  $C_r$ ,  $L_r$ , and  $L_m$ . As a result, the current becomes sinusoidal, and the power delivered to the converter’s output is mainly derived from the fundamental frequency component. The input voltage is therefore expressed using the first harmonic approximation, as shown in (1).

$$V_{dFHA} = (4 \cdot V_{Bus} / 2 \cdot \pi) \sin(\omega t) \tag{1}$$

**2.5. Equivalent resistance**

Figure 4 shows a simplified schematic of a half-bridge LLC resonant converter, where  $L_m$  is the magnetizing inductance,  $L_r$  is the series resonant inductance, and  $C_r$  is the resonant capacitor. It also presents the

typical waveforms of the LLC resonant converter. The operating frequency is assumed to match the resonant frequency, determined by the resonance between  $L_r$  and  $C_r$ . Since the magnetizing inductance is relatively low, a significant magnetizing current  $I_m$  flows freely on the primary side without contributing to power transfer. The primary current  $I_p$  is the sum of the magnetizing current and the reflected secondary current.

In general, the second stage of the LLC resonant topology consists of three main parts, as illustrated in Figure 4: a square-wave generator, a resonant tank circuit, and a fast-output rectification stage. The resonant circuit consists of a capacitor, leakage inductances, and the magnetizing inductance of the transformer. It acts as a filter for high-order harmonic currents. In practice, only a sinusoidal current can flow through the resonant tank, even when a square-wave voltage is applied to it. The primary current  $I_p$  lags behind the voltage applied to the resonant circuit, namely, the fundamental component of the square-wave voltage  $V_d$  generated by the half-bridge totem enabling ZVS of the MOSFETs. The rectifier stage generates a DC output voltage by rectifying the AC current using diodes and a filter capacitor  $C_0$ . The rectifier can be implemented either as a full-bridge configuration or a center-tap structure with capacitive output filtering.

Thanks to the filtering action of the resonant circuit, the fundamental approximation can be used to determine the voltage gain of the resonant converter. This approximation assumes that only the fundamental component of the input square wave contributes to power transfer toward the output. Since the secondary-side rectifier acts as an impedance transformer, the equivalent load resistance differs from the actual load resistance. Figure 5 illustrates the model of this equivalent load resistance. The primary circuit is represented by a sinusoidal current source  $i_{sFHA}$ , and a square-wave voltage  $V_s$  appears at the rectifier input. The output current  $i_{sFHA}$  is then determined as (2):

$$I_{SFHA} = (I_{LED} * \pi / 2) \sin(\omega t) \tag{2}$$

$V_{SFHA}$  is given as (3) and (4):

$$V_{SFHA} = +V_{LED} \text{ if } \sin(\omega t) > 0 \tag{3}$$

$$V_{SFHA} = -V_{LED} \text{ if } \sin(\omega t) < 0 \tag{4}$$

The fundamental harmonic equation of  $V_{SFHA}$  is given as (5):

$$V_{SFHA} = (4 * V_{LED} / \pi) \sin(\omega t) \tag{5}$$

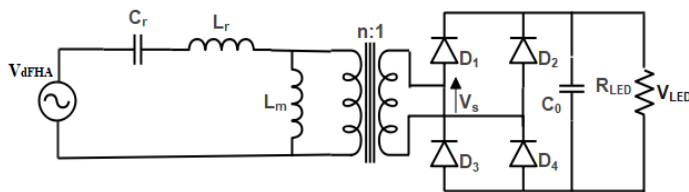


Figure 4. Simplified AC equivalent circuit of the LLC converter

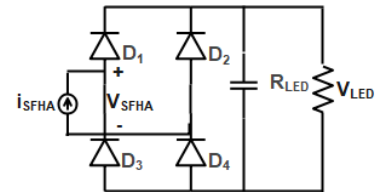


Figure 5. Derivation of the equivalent load resistance  $R_{ac}$

After this process, the voltage and current at the transformer primary become sinusoidal and in phase with each other. The transformer, rectifier, output filter, and load can therefore be replaced by an equivalent resistance connected in parallel with the magnetizing inductance  $L_m$ . Since the harmonic component of  $V_{SFHA}$  does not contribute to power transfer, the equivalent AC load resistance on the secondary side can be calculated by dividing  $V_{SFHA}$  by  $I_{SFHA}$ , as shown in (6), and the equivalent circuit model is illustrated in Figure 6.

$$R_{ac_s} = V_{SFHA} / I_{SFHA} = 8 * V_{LED} / \pi^2 * I_{LED}, R_{ac_s} = \frac{8}{\pi^2} * R_{LED} \tag{6}$$

We now proceed to the next step, which consists of transferring the resistance  $R_{acs}$  from the secondary side to the primary side. This can be achieved using the transformer turns ratio and the resistance transformation equation. Given the turns ratio ( $n = \frac{N_p}{N_s}$ ), the equivalent load resistance  $R_{acs}$  referred to the primary side is obtained as (7).

$$R_{ac_p} = \frac{8 * n^2}{\pi^2} * R_{LED} \tag{7}$$

After applying the necessary steps for the first harmonic approximation, the circuit in the referenced figure can be analyzed in its simplified form, as illustrated in Figure 7.

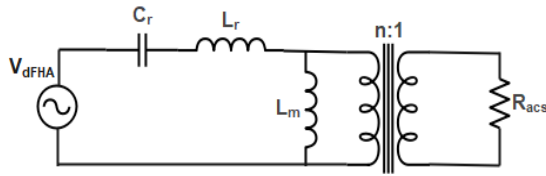


Figure 6.  $R_{acs}$  Approximation of the output circuit

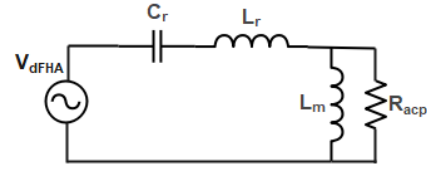


Figure 7. Simplified output circuit of the converter

**2.6. Transfer function of the LLC-led driver**

The LLC resonant circuit, simplified using the first harmonic approximation of the square-wave signals, is illustrated in Figure 8. This approximation allows the complex switching waveforms to be represented by their fundamental sinusoidal component, which simplifies the analysis of the resonant behavior. The model provides an effective way to study the voltage and current characteristics of the converter under steady-state operation. Therefore, it is widely used in the design and optimization of high-efficiency LLC resonant converters.

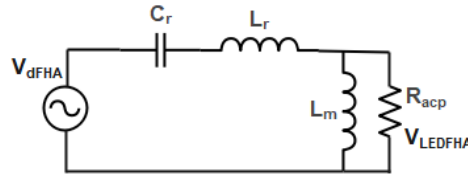


Figure 8. AC equivalent circuit of the proposed LED driver

The equivalent electrical circuit is a voltage divider: the voltage ratio is equal to the ratio of the impedances.

$$M(p) = \frac{V_{LEDFA}(p)}{V_{dFHA}(p)} = \frac{Z_p}{Z_s + Z_p} \tag{8}$$

$$\begin{cases} Z_s(p) = L_r * P + \frac{1}{C_r * P} \\ \frac{1}{Z_p} = \frac{1}{R_{acp}} + \frac{1}{L_m * P} \end{cases} \rightarrow \begin{cases} Z_s(p) = L_r * P + \frac{1}{C_r * P}, P = j\omega \\ Z_p(p) = \frac{L_m * P}{1 + (\frac{L_m}{R_{acp}}) * P} \end{cases} \tag{9}$$

$$M(j\omega) = \frac{V_{LEDFA}}{V_{dFHA}} = \frac{(m-1)(\frac{\omega}{\omega_0})^2}{(\frac{\omega^2}{\omega_p^2} - 1) + (\frac{Q(m-1)}{\omega_0})(\frac{\omega^2}{\omega_0^2} - 1) * j\omega} \tag{10}$$

$$M_v = \frac{V_{LEDFA}}{V_{dFHA}} = \frac{V_{sFHA} * n}{V_{dFHA}} = \frac{4n * V_{led} * \sin(\omega t)}{4 * V_{Bus} * \sin(\omega t)} = \frac{2n * V_{led}}{V_{Bus}} \tag{11}$$

Or:

$$Q = \frac{1}{R_{acp}} \sqrt{\frac{L_r}{C_r}}, \omega_p = \frac{1}{\sqrt{L_p * C_r}}, \omega_0 = \frac{1}{\sqrt{L_r * C_r}}, R_{acp} = \frac{8 * n^2}{\pi^2} * R_{LED} \tag{12}$$

$$L_p = L_r + L_m, m = \frac{L_p}{L_r}, M_v = \sqrt{\frac{m}{m-1}} * a, \omega_0 = \omega \tag{13}$$

As shown in (10), there are two resonance frequencies: one determined by  $L_r$  and  $C_r$ , and the other determined by  $L_p$  and  $C_r$ . In (14) indicates that the voltage gain is equal to unity at the resonance frequency ( $\omega_0$ ), regardless of load variations, and is given by (14).

$$M_v = \frac{(m-1) \cdot \omega_p^2}{\omega_0^2 - \omega_p^2} = \frac{2n \cdot V_{led}}{V_{Bus}} = 1 \quad a\omega = \omega_0 \quad (14)$$

## 2.7. LED selection

For this work, 5730-type LEDs were selected, each rated at 0.5 W, operating at a forward voltage between 3 V and 3.4 V with a nominal current of 150 mA. To form a 50 W module, two strings of ten LEDs connected in series were assembled in parallel. Three of these 50 W modules were then connected in parallel, achieving a total power of 150 W. The supply voltage of the system is between 30 V and 34 V ( $V_{LED}$ ).

## 2.8. Calculation of resonant circuit parameters

According to the relation:  $P_{Led} = V_{Led} * I_{Led}$ :

$$I_{Led} = 4.69A \quad (15)$$

We also have:  $P_{Led} = R_{Led} * i_{Led}^2$ . Thus, the LED resistance is calculated as (16).

$$R_{led} = 6.82\Omega \quad (16)$$

For the input voltage amplitude  $V_{dFHA}$ , we take the value of the fundamental harmonic:

$$V_{dFHA} = \frac{4 * (V_{bus}/2)}{\pi} = 254.6 V \quad \text{with } V_{Bus} = 400 V \quad (17)$$

For the LED voltage amplitude  $V_{LEDFA}$ , we also take the value of the fundamental harmonic:

$$V_{LEDFA} = \frac{4 * V_{LED}}{\pi} = 41 V \quad (18)$$

The filter gain is calculated by (19).

$$Mv = \sqrt{\frac{m}{m-1}} = 1.12, \quad m = 5 \quad (19)$$

Transformer turns ratio selection:

$$n = \frac{N_p}{N_s} = \frac{V_{Bus}}{2 * V_{LED}} * M_v \quad (20)$$

$$n = 7$$

The equivalent LED resistance in the simplified model  $R_{acp}$  is determined by (21).

$$R_{acp} = \frac{8 \cdot n^2}{\pi^2} * R_{LED} = 270, 88 \Omega \quad (21)$$

The quality factor is set to:  $Q = 0.4 < 1$ . Therefore, for the series resonant circuit parameters, imposing  $Q$  and  $\omega_0 = 2\pi * f_0$ , we have:

$$Z_r = Lr * \omega_0 = \frac{1}{Cr * \omega_0} \implies Z_r = R_{acp} * Q, \quad Zr = \sqrt{\frac{Lr}{Cr}} \quad (22)$$

$$Lr = \frac{R_{acp} * Q}{\omega_0} \quad \text{and} \quad Cr = \frac{1}{Q * \omega_0 * R_{acp}} \quad (23)$$

Finally, the magnetizing inductance  $L_p$  is defined by the inductance ratio:  $m = L_p / L_r = 5$ . ( $L_p = L_m + L_r$ ) A sufficient value of  $m$  ensures current stability through the LEDs. The parallel resonant frequency is given by:

$$\omega_p = \frac{1}{\sqrt{(Lr + Lm) \cdot Cr}} \quad (24)$$

## 2.9. Calculated parameters

Finally, based on the design of the resonant circuit, the calculated passive component values are summarized in Table 1. These parameters are derived from the proposed design methodology, considering the required operating conditions of the LLC resonant converter. The selection of these components ensures optimal resonant behavior, improved efficiency, and stable operation under varying load conditions.

Table 1. Calculated parameters of the proposed LED driver

Parameters	Desing	Parameters	Desing
$L_m$	688 $\mu$ H	m	5
$L_r$	172 $\mu$ H	Q	0.4
$C_r$	14.68 nF	$M_v$	1.12
$f_0$	100 KHZ	n	7

### 2.10. Bode diagram

The Bode diagram of the system is shown in Figure 9. It highlights the frequency response of the proposed filter, clearly illustrating the lower and upper cutoff frequencies as well as the corresponding bandwidth. This analysis makes it possible to assess the system's stability and dynamic behavior, confirming the effectiveness of the filter within the intended operating range.

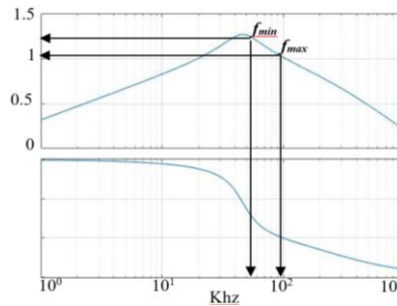


Figure 9. Bode diagram of the system

### 2.11. Determination of maximum and minimum voltage gains

The maximum and minimum voltage gains are calculated as (25) and (26):

$$M_{min} = \frac{2 \cdot V_{LED}}{V_{Busmax}} * n = \frac{2.32}{410} * 7 = 1.09 \quad (25)$$

$$M_{max} = \frac{2 \cdot V_{LED}}{V_{Busmin}} * n = \frac{2.32}{390} * 7 = 1.14 \quad (26)$$

To prevent the operating point from entering the capacitive region, the maximum voltage gain must include a design margin. This margin is set to  $0.15 \times M_{max}$ . Therefore, the value of  $M_{max}$  is adjusted as (27):

$$M_{max} = 1.14 * 1.15 = 1.31 \quad (27)$$

### 2.12. Determination of the switching frequency range

The minimum switching frequency  $f_{min}$  and the maximum switching frequency  $f_{max}$  are calculated and presented:

$$f_{max} = \frac{1}{2 \cdot \pi \cdot \sqrt{L_r \cdot C_r}} = 99 \text{ KHz} \quad (28)$$

$$f_{min} = \frac{f_r}{\sqrt{1 + K \left(1 - \frac{1}{M_{max}^2}\right)}} = 61.7 \text{ KHz}, k = \frac{L_m}{L_r} \quad (29)$$

## 3. IMPLEMENTATION

Figure 10 presents the overall functional block diagram of the developed system. It includes a control board designed to drive the half-bridge inverter as well as the measurement devices. The LED driver integrates both the half-bridge inverter and the LLC resonant circuit, supplied by a DC bus voltage ( $V_{BUS}$ ) generated from a PFC stage. The complete system drives a 150 W 5730-type LED lamp.

Although the integrated transformer approach in LLC resonant converter design allows combining the magnetic components  $L_r$  and  $L_m$  into a single core thus reducing the magnetic component count—the value of  $L_r$  is difficult to control in the practical design of a transformer. Designing the resonant circuit sometimes requires iterative adjustments to account for the final  $L_r$  value obtained after transformer construction. The final design of the resonant network is summarized in Table 1.

### 3.1. Final resonant network design

To evaluate the efficiency of the proposed LED driver, a prototype was built and tested. Table 2 summarizes the system specifications of the proposed converter along with the characteristics of the components employed. The design process considered several key parameters, including LED selection, transformer turns ratio ( $n$ ), maximum ( $M_{\max}$ ) and minimum ( $M_{\min}$ ) voltage gain, effective resistive load reflected to the transformer primary ( $R_{\text{acp}}$ ), inductance ratio ( $m$ ) between magnetizing and resonant inductances, quality factor ( $Q$ ), resonant frequency ( $f_r$ ), and the values of the series resonant capacitor ( $C_r$ ), resonant inductance ( $L_r$ ), and magnetizing inductance ( $L_m$ ).

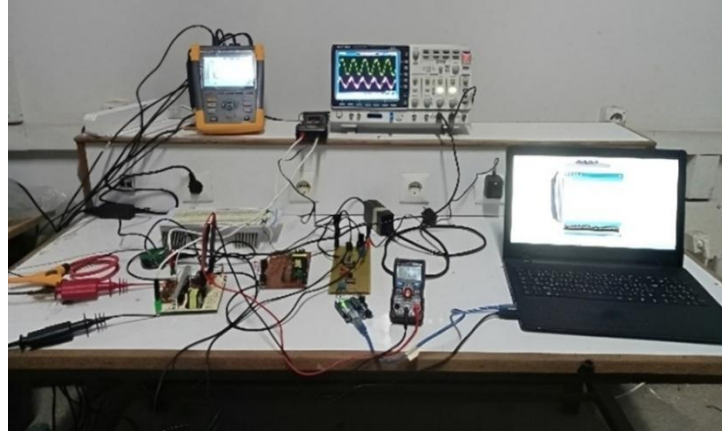


Figure 10. Photo of the proposed prototype

Table 2. Practical specifications of the proposed LED driver

Parameters	Final design	Parameters	Final design
$L_p$	580 $\mu\text{H}$	$m$	4.9
$L_r$	118 $\mu\text{H}$	$Q$	0.4
$C_r$	15 nF/1000V	$M_v$	1.12
$f_0$	98 KHZ	$n$	7

### 3.2. Experimental result

Experimental tests were performed on the developed LLC-based LED driver to validate the theoretical calculations and simulation results. The prototype integrates a half-bridge inverter stage along with a PFC front-end. As an initial step, gate drive signals were tested to ensure proper operation. Figure 11 shows the measured gate voltages applied to the MOSFETs at a switching frequency of 98 kHz, confirming compliance with the design specifications. Figure 12 depicts the measured waveforms of  $V_d$  and  $V_{\text{dFHA}}$ , whereas Figure 13 shows  $V_s$  and  $I_s$ . Under nominal load conditions, Figure 14 illustrates the resonant capacitor voltage ( $V_{\text{cr}}$ ), the resonant inductor current ( $i_{Lr}$ ), and the voltage  $V_d$  within the LLC resonant tank. Finally, Figure 15 presents the measured voltage and current across a 150 W LED lamp in steady-state operation, demonstrating stable performance and high-quality power delivery from the driver.

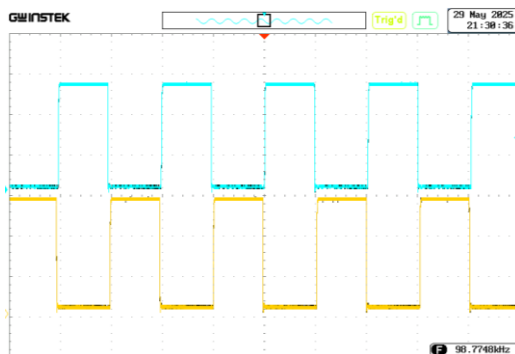


Figure 11. Waveforms at rated load  $V_{g1}; V_{g2}$

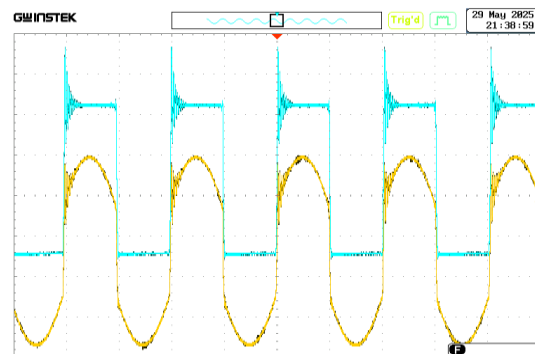


Figure 12. Waveforms at rated load  $V_d; V_{\text{dFHA}}$

### 3.3. Study of total harmonic distortion and power factor correction of the input current and improved results discussion

The analysis shows that the proposed system with a PFC stage reduces the THD of the input current from over 134% (Figure 16) to around 17% (Figure 17). This significant reduction demonstrates improved power quality and compliance with electrical grid harmonic standards. In terms of efficiency, the developed prototype achieves a measured conversion efficiency exceeding 95%. This performance is comparable to or superior to several reported LED driver architectures. For example, the CrCM boost PFC combined with an LLC resonant converter in [6] reaches efficiencies around 92–94%, while the single-stage soft-switching driver in [7] achieves approximately 90%. Similarly, the high-brightness LED driver presented in [12] reports efficiencies near 94%. The proposed design, therefore, offers improved efficiency while simultaneously reducing THD more effectively than many existing solutions.

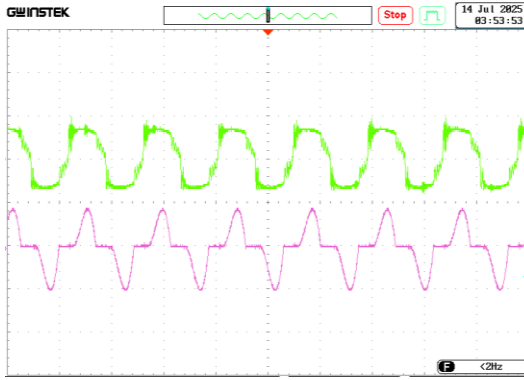


Figure 13. Waveforms at rated load  $V_s$  ;  $I_s$

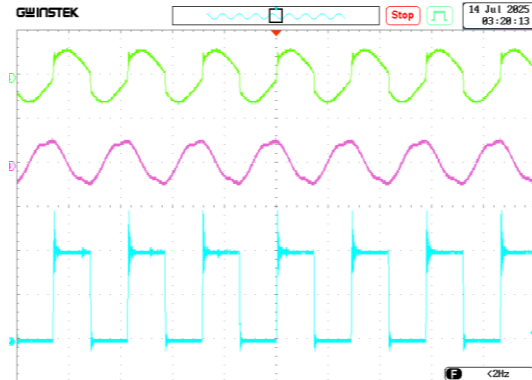


Figure 14. Waveforms at rated load  $V_{cr}$  ;  $i_{Lr}$  ;  $V_d$



Figure 15. Obtained the current–voltage result of the LEDs

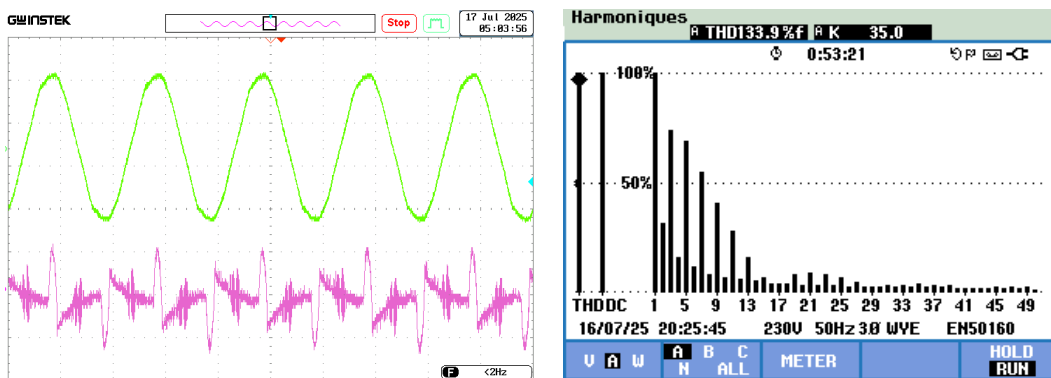


Figure 16. Voltage and current and THD analysis of current AC without PFC

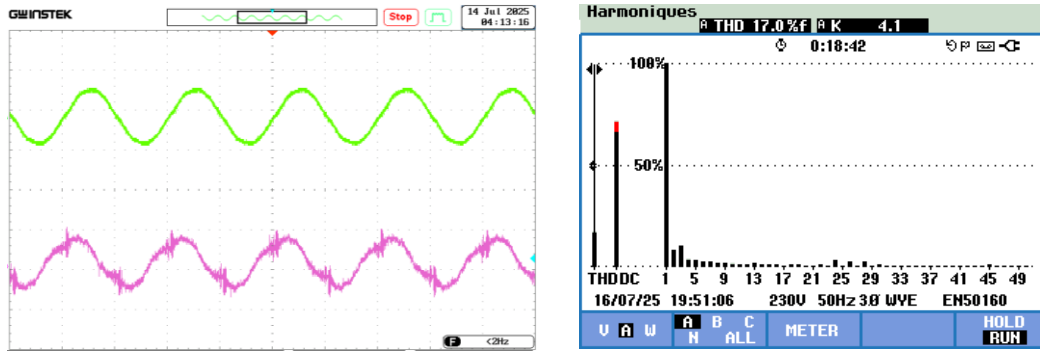


Figure 17. Voltage and current and THD analysis of current AC with PFC

**4. CONCLUSION**

This study designed and experimentally validated a 150 W two-stage LED driver integrating a high-performance PFC stage and a half-bridge LLC resonant converter for public lighting applications. The proposed architecture effectively addresses the limitations identified in conventional LED drivers by providing stable output regulation, soft-switching operation, and improved compatibility with grid power quality requirements. The experimental results demonstrate significant performance improvements. The input current THD was reduced from more than 134% to approximately 17%, the power factor reached values close to 0.99, and the overall efficiency exceeded 95%. These results confirm the effectiveness of combining an advanced PFC front-end with an optimized LLC resonant stage to achieve high efficiency and grid-compliant operation in outdoor lighting systems.

Despite its strong performance, the system presents certain limitations. The practical design of the transformer, particularly the precise tuning of the resonant inductances, requires iterative adjustments. Moreover, thermal management becomes increasingly important at higher power levels or in enclosed lighting fixtures. Future work may explore the use of adaptive or digital control techniques, integration with smart grid infrastructures and communication-based lighting networks, as well as scaling the proposed design to higher-power LED systems suitable for next-generation urban lighting applications.

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**AUTHOR CONTRIBUTIONS STATEMENT**

This journal uses the Contributor Roles Taxonomy (CRediT) to recognize individual author contributions, reduce authorship disputes, and facilitate collaboration.

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C : Conceptualization  
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 Va : Validation  
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Vi : Visualization  
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 P : Project administration  
 Fu : Funding acquisition

**CONFLICT OF INTEREST STATEMENT**

Authors state no conflict of interest.

## DATA AVAILABILITY




The data and simulation models used in this study are available from the author upon reasonable request.

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